

## **Program Details**

Program Name: MBot for BeginnersProgram Code: TRA0009Duration: 1.5 hrs per Lesson (approx. 3 months to complete the<br/>course)Learning Material : mBot (exclusive)

## **Program Outline**

Lesson 1: Introduction of mBot hardware and its application

Lesson 2: MBot programming development environment and Scratch

programming

Lesson 3: Motor control

Lesson 4: Light sensor and buzzer

Lesson 5: Ultrasonic sensor and its application

Lesson 6: Programming process control

Lesson 7: Introduction of For Loop

Lesson 8: Introduction of If... else

Lesson 9: Introduction of variables

Lesson 10: Data and computations

Lesson 11: Controlling mBot with smart devices and the line follower program

Lesson 12: Custom Blocks (functions) and obstacle avoidance program



## **Learning Outcomes**

At the end of this course, students will be able to:

- 1. Complete the assembly of his/her first robot and ensure that the components are securely mounted.
- 2. Identify the name of the parts inside the kits and understand how to use it.
- 3. Use the basic tools and understand the dimensions of all the fastening parts.
- 4. Understand programming process and to write the first mBlock program.
- 5. Locate and identify various functionalities in the mBlock software interface.
- 6. Use various ways to establish connection between the mBot and computer.
- 7. Can creatively complete the construction of basic functional structure as needed.
- 8. Identify the name of different sensors and their applications.
- 9. Understand how the motor receives data from other sources which in turn, become the source to its speed.
- 10.Understand the arrays of lists and the use of subprograms in the mBlock development environment.
- 11.Understand when to use loop and switch, as well as their uses.
- 12. Understand the definition and principle of the input of mBot ultrasonic sensor and the various ways of using mBot ultrasonic sensor.
- 13.Understand the definition and principle of the input of an mBot's of a line-follower sensor and its application.
- 14. Understand the principle of the transmitter and receiver ends of the mBot IR sensor and its applications.
- 15.Understand the principle of the transmitter and receiver of the mBot's light sensor and its applications.
- 16.Understand the functions and principles of the mBot's button, buzzer, LED lights and reset button.
- 17.Understand the basic concept and application of the mBot Bluetooth communications module.